

Centre for Robotics and Automation 香港城市大學 City University of Hong Kong

## System Identification with Few Samples

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## Abstract

System identification has long been a topic of interest in control community, and many classic algorithms are successively derived and proved to be asymptotically unbiased, such as the Ho-Kalman algorithm and the subspace methods. However, when only few or moderate amount of samples are available, the ill-conditionedness of certain algorithms are observed both in theory and in practice. In this talk, we first provide an analysis on the ill-conditioned problem, and prove that both the Ho-Kalman algorithm and the identification problem itself are ill-conditioned. Specifically, the result also shows that the system poles are hard to identify. Motivated by this observation, we then introduce a new identification algorithm by constructing another system with predefined system poles to approximate the input-output relationship of the true system. Both theoretical analysis and numerical results demonstrate the efficiency of the proposed algorithm.

## Biography

Jiayun Li received her Bachelor of Engineering degree from Department of Automation, Tsinghua University, Beijing, China, in 2022. She is currently a second-year Ph.D. student in the Department of Automation, Tsinghua University. Her research interests include system identification with its applications in robotics.

## All are welcome

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